



ScanTronic™

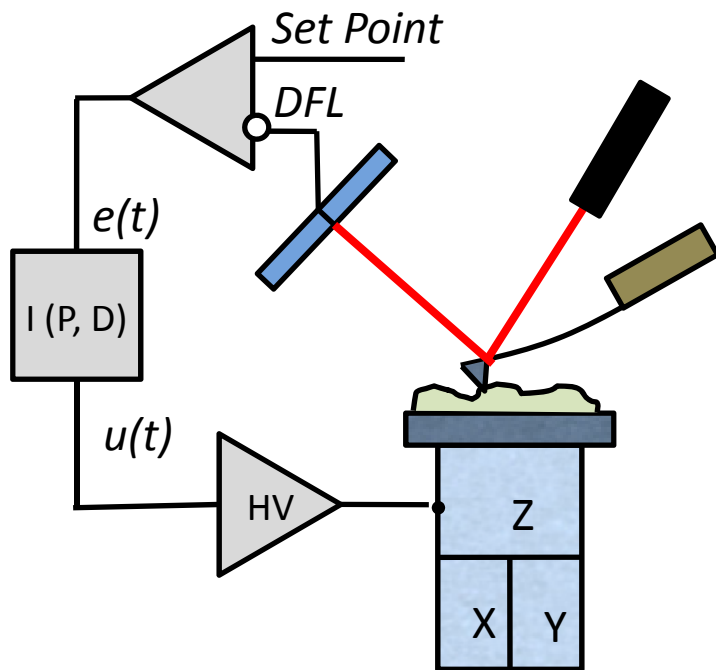
a Shortcut to Reliable AFM results

Dr. Vyacheslav Polyakov,
Director of R&D

Agenda

- Introduction
- Motivation for the development of ScanTronic™ and RapidScan™ technologies
- Automated optimization of scanning parameters in tapping mode AFM: physical background, basics of the algorithms and examples of application
- Rapid scanning
- Summary

Intro: Atomic Force Microscopy

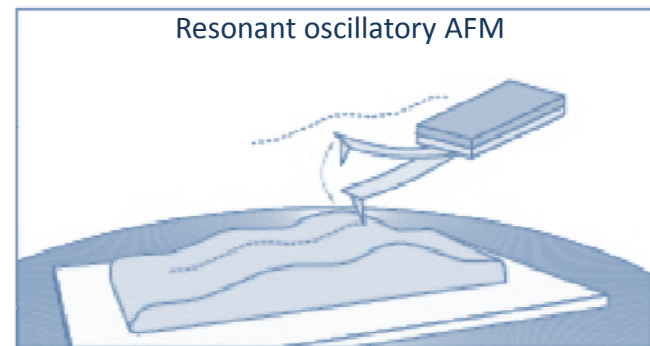
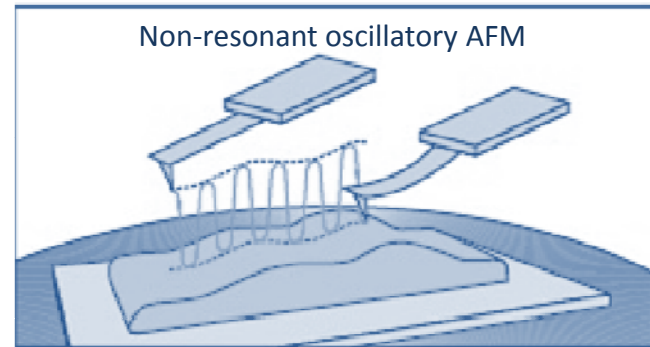
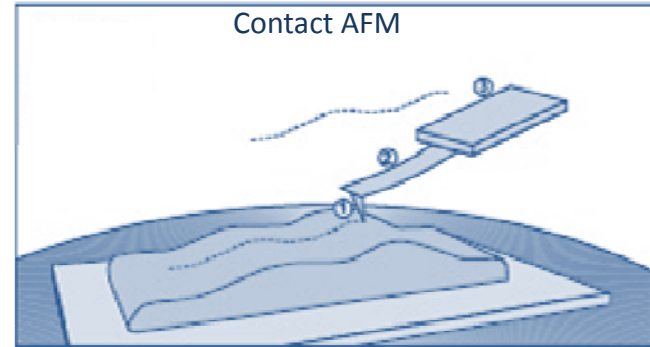
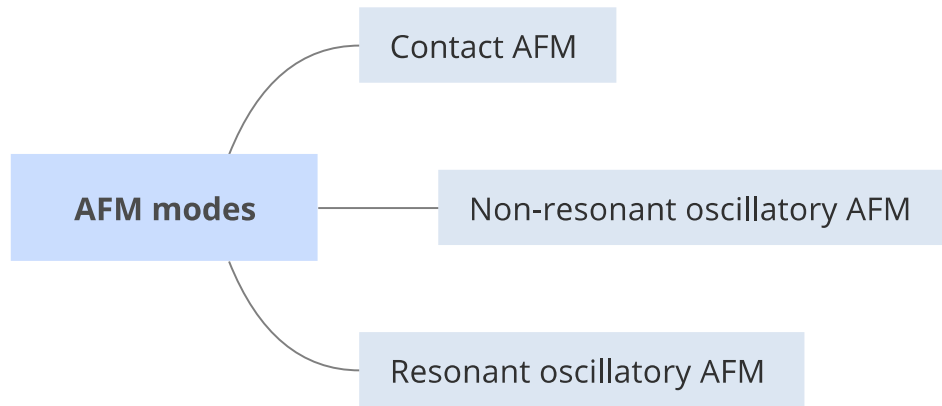


- 3D-imaging of surface topography with (sub-)nm spatial resolution
- Imaging of nanomechanical, electrical, magnetic and other surface properties with nm-scale spatial resolution (*"more than 50 AFM modes"*)
- Can be combined with optical techniques in UV, visible, IR and THz ranges (AFM-Raman, nano-IR AFM, IR and THz s-SNOM)
- Can be used under different environments (vacuum, liquid, controlled atmosphere, temperature variations, etc.)
- Field of view: up to $\approx 100 \mu\text{m}$ in X and Y; $\approx 10 \div 20 \mu\text{m}$ in Z
- Scan rate: $1 \div 2 \text{ Hz}$

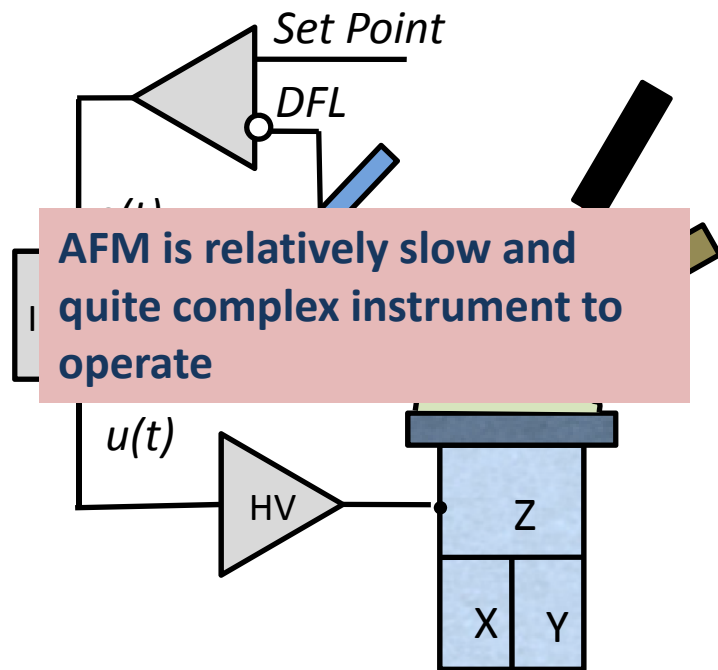
Intro: NT-MDT SI Product Line

AFM				AFM-Raman / IR / TERS	
 <p>RD 100 2011</p>	 <p>RD 100 2009</p>				
SOLVER NANO	NEXT/TITANIUM	NTEGRA	VEGA	NTEGRA SPECTRA II	NTEGRA Nano IR
<ul style="list-style-type: none"> • Compact desktop AFM/STM for both education and science • Full set of AFM/STM modes • High AFM/STM performance • Closed-loop Scanner 	<ul style="list-style-type: none"> • AFM/STM with exceptional level of automation • Fast, precise and low-noise closed-loop scanner • High resolution imaging due to extremely low noise and high stability • Full set of standard and advanced AFM/STM modes • HybriD Mode™ 	<ul style="list-style-type: none"> • Modular high performance AFM/STM for wide range of applications • Low noise and high resolution • Full set of standard and advanced AFM/STM modes • HybriD Mode™ 	<ul style="list-style-type: none"> • Automated high-resolution AFM for up to 200x200 mm samples • Ultra stable AFM • Full set of standard and advanced AFM modes • HybriD Mode™ • ScanTronic™ 	<ul style="list-style-type: none"> • SPM • Automated AFM laser, probe and photodiode • Confocal Raman / Fluorescence / Rayleigh Microscopy • Tip Enhanced Raman Scattering (TERS) • TERS optimized system for all possible excitation/detection geometries • HybriD Mode™ 	<ul style="list-style-type: none"> • IR sSNOM system • High resolution AFM • Stabilized CO₂ laser • HybriD Mode™

Intro: Basic AFM Modes

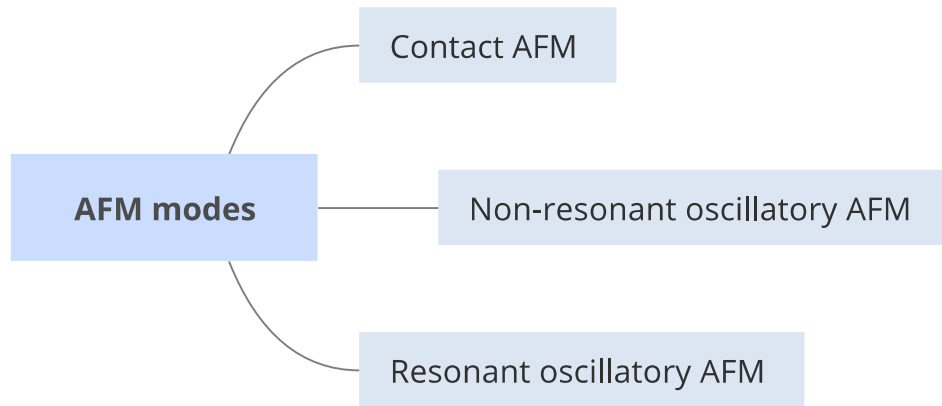


Motivation: Atomic Force Microscopy

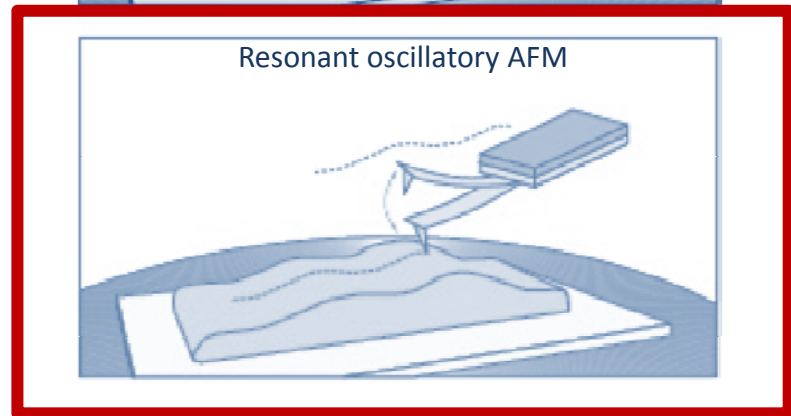
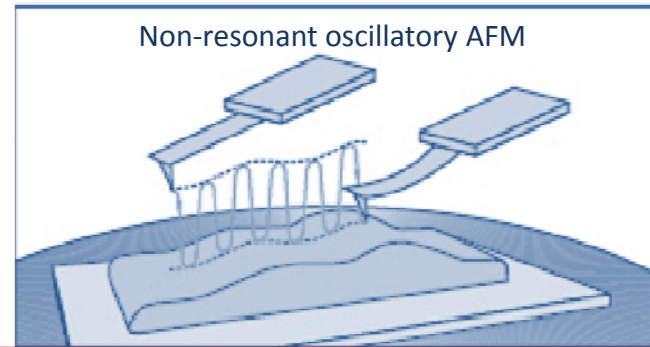
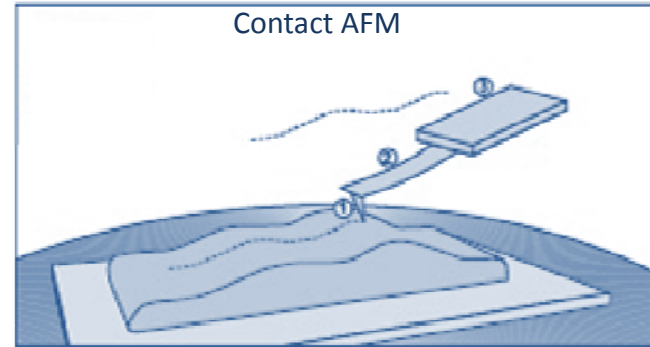


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Motivation: Basic AFM Modes



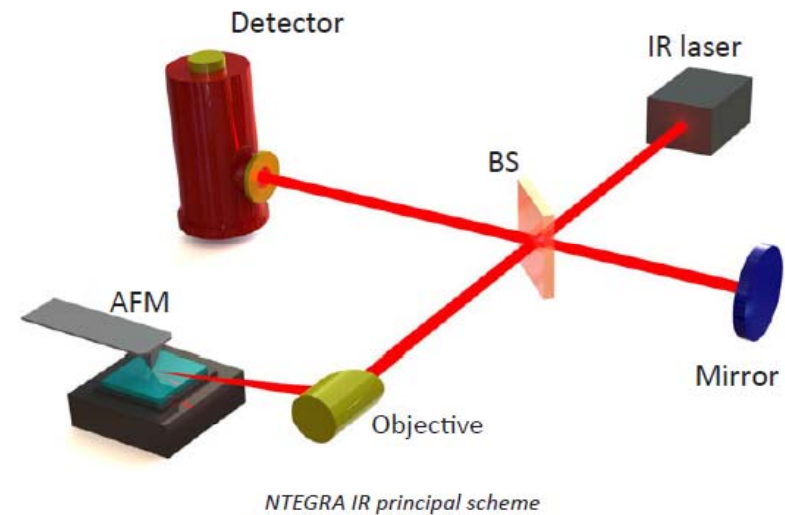
Tapping mode:
about 90% of publications where AFM is used



Motivation: VEGA AFM



Motivation: NTEGRA Nano IR – IR s-SNOM measurements

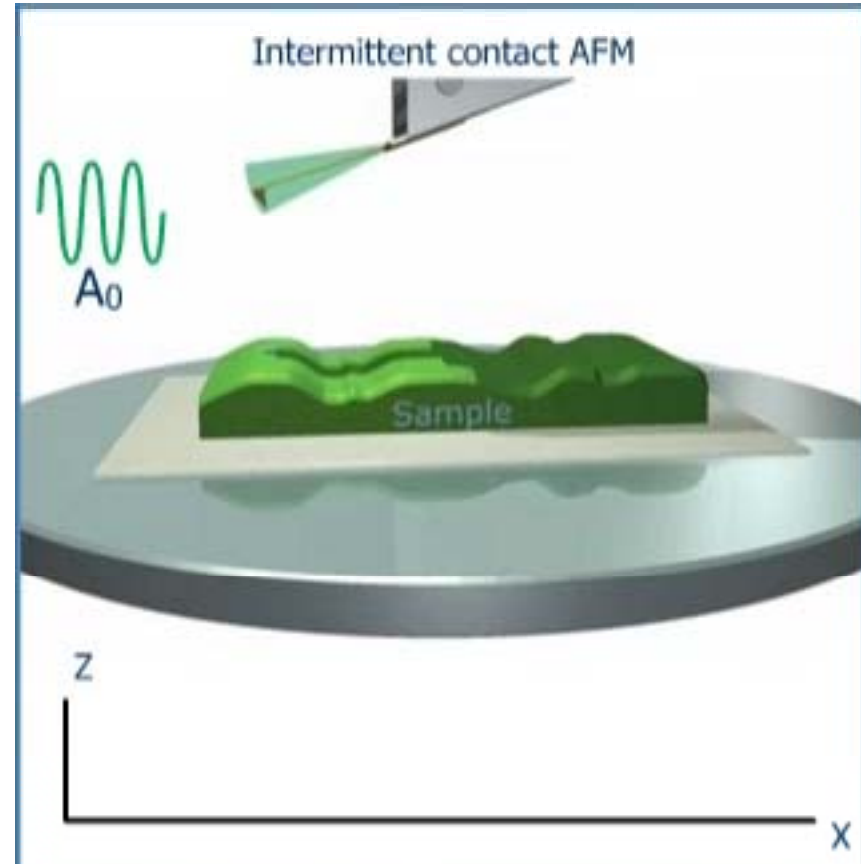
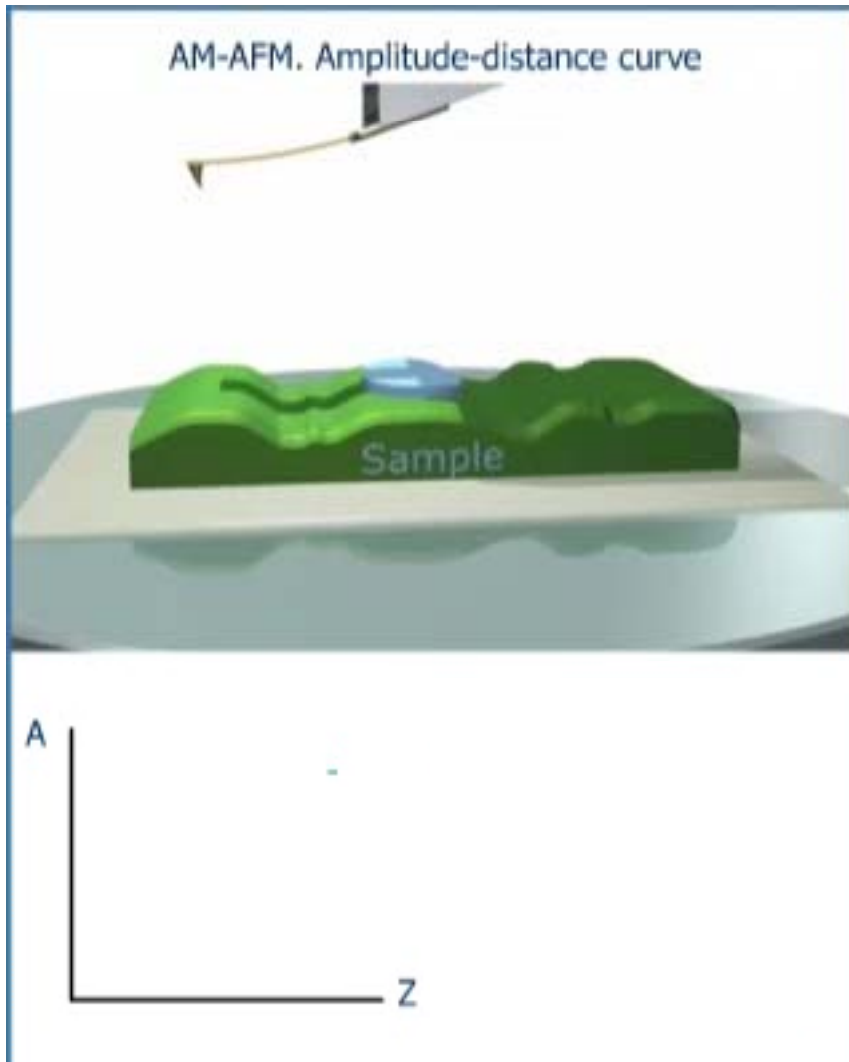


- IR s-SNOM microscopy and spectroscopy with 10 nm spatial resolution
- Wide spectral range of operation: 3-12 μm
- Incredibly low thermal drift and high signal stability
- Versatile AFM with advanced modes: SRI (conductivity), KPFM (surface potential), SCM (capacitance), MFM (magnetic properties), PFM (piezoelectric forces)
- HybriD Mode™ - quantitative nanomechanical mapping
- Integration with microRaman (optional)

**Automated optimization of scanning parameters
in tapping mode AFM:**

physical background, basics of the algorithms and examples of
application

Tapping (semicontact) AFM



Automated optimization of scanning parameters

Key scanning parameters:

- A_0 – Amplitude of cantilever oscillations
- **SP** – Set point amplitude
- k_i – Integral feedback gain
- V_x – Scan speed

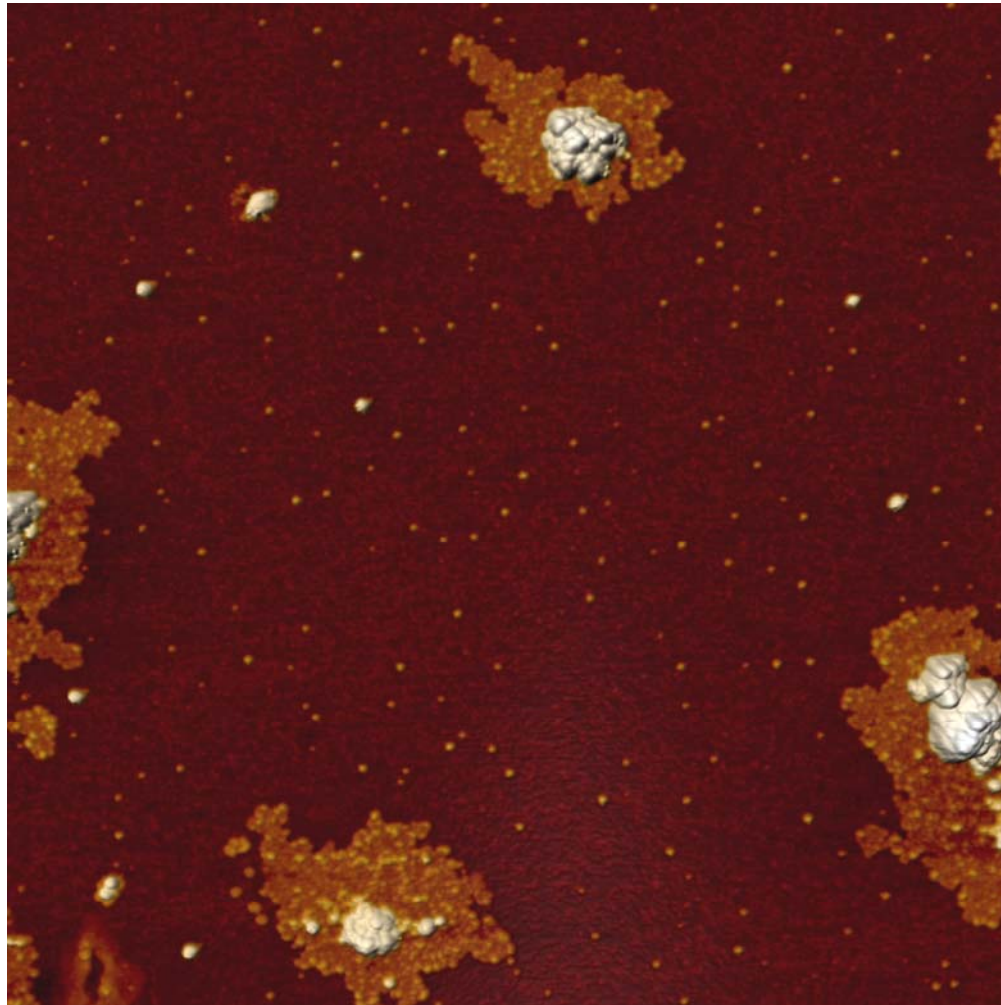
Additional scanning parameters:

- **LP** – low-pass filter band
- k_p - Proportional feedback gain

Known parameters:

- **Probe parameters:** resonant frequency, Q-factor
- Mag to amplitude slope conversion
- Sample roughness (?)

Automated optimization of scanning parameters



Fluoroalkanes F₁₄H₂₀ on Si.
Scan size 5×5 μm

Automated optimization of scanning parameters

Is it possible to **automatically optimize** scanning parameters while operating in **tapping mode** AFM to measure the topography and phase contrast?

- How feedback system works in tapping mode AFM?
- Parachuting effects
- Mode switching in tapping mode AFM
- How to optimize integral feedback gain for tapping mode AFM?

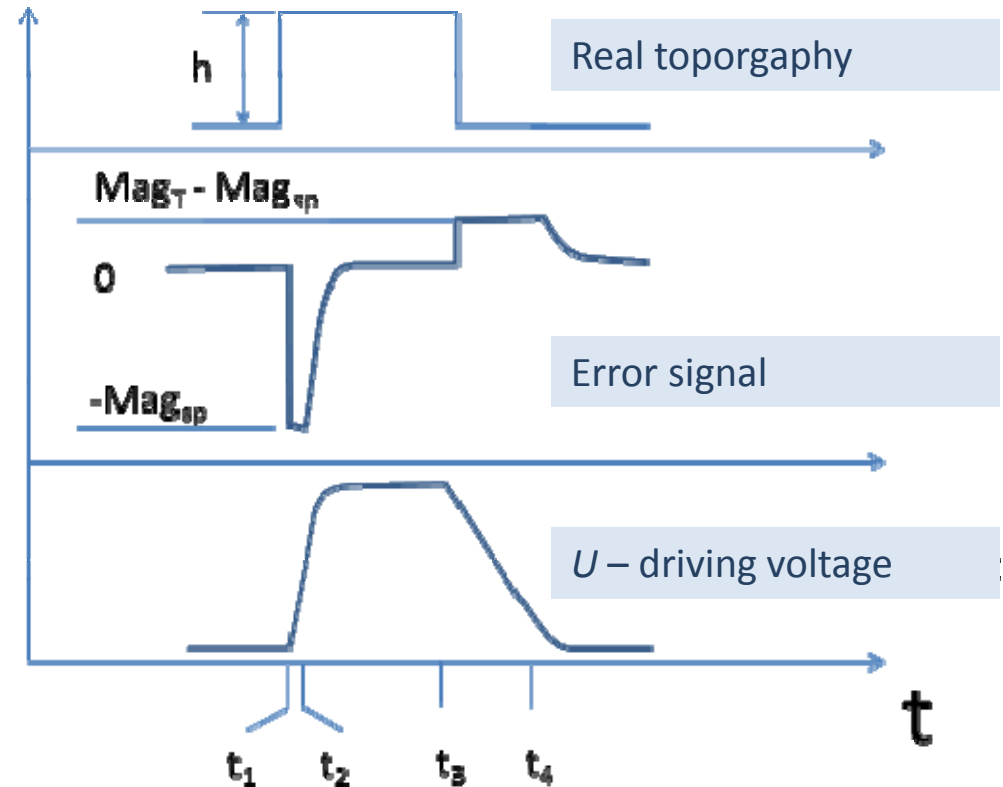
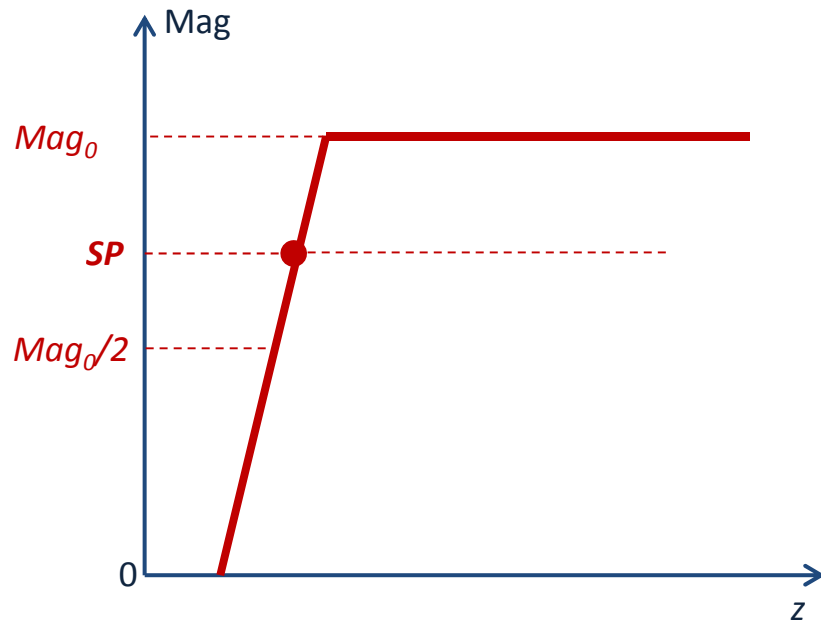
What should be objective function for optimization?

Parachuting effect in tapping mode AFM

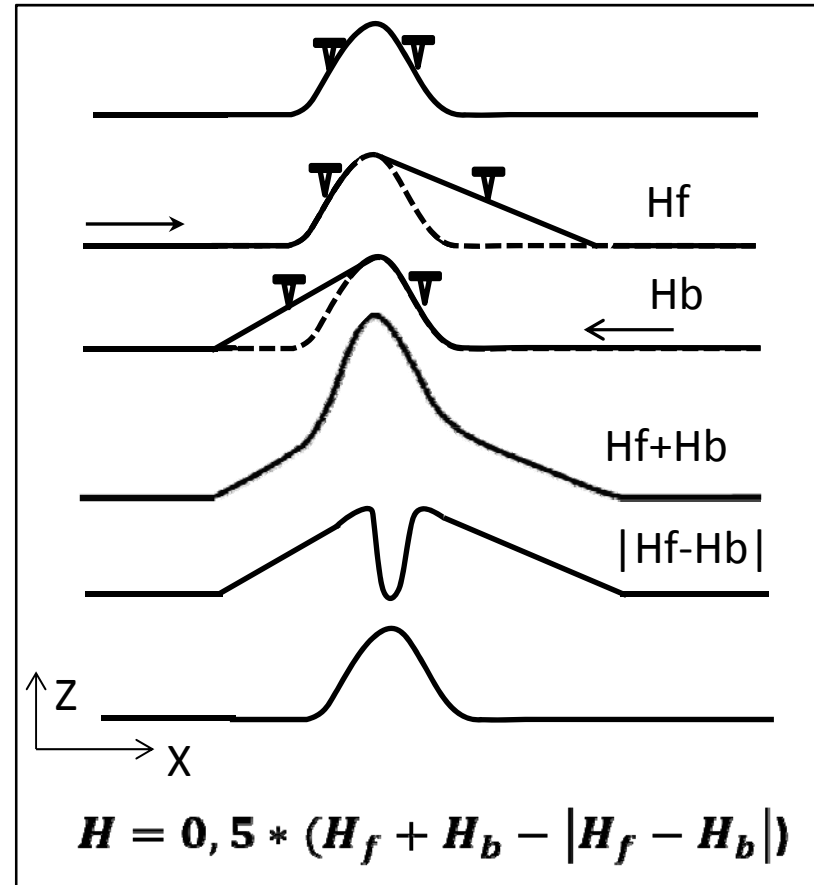
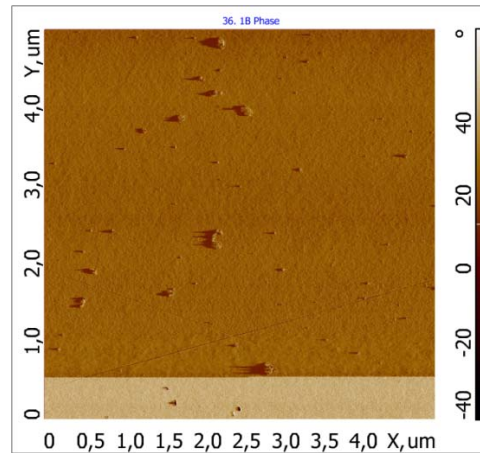
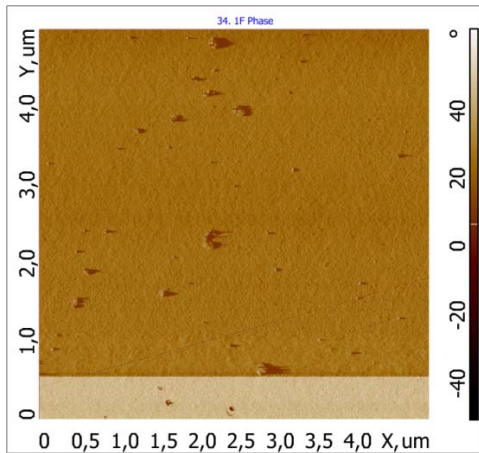
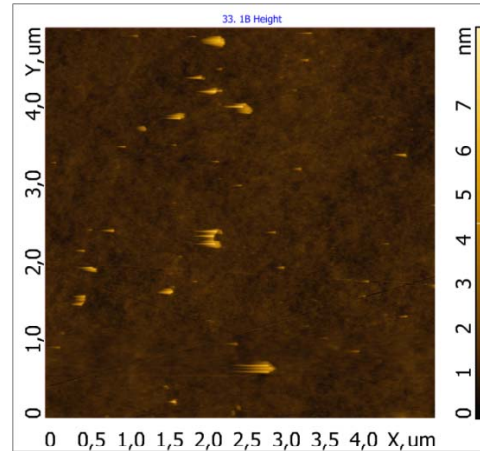
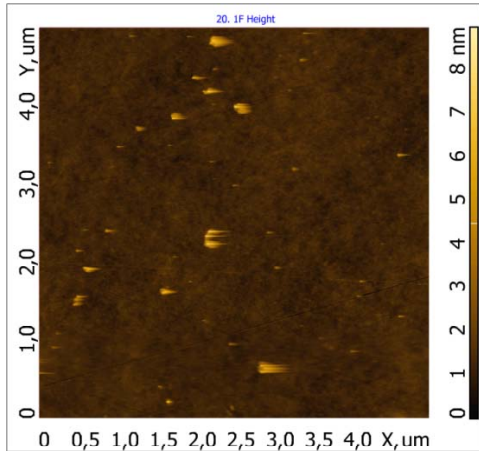
$$-SP \leq \varepsilon \leq Mag_0 - SP$$

$$\frac{dU}{dt} = k_i \cdot \varepsilon = k_i(Mag_0 - SP)$$

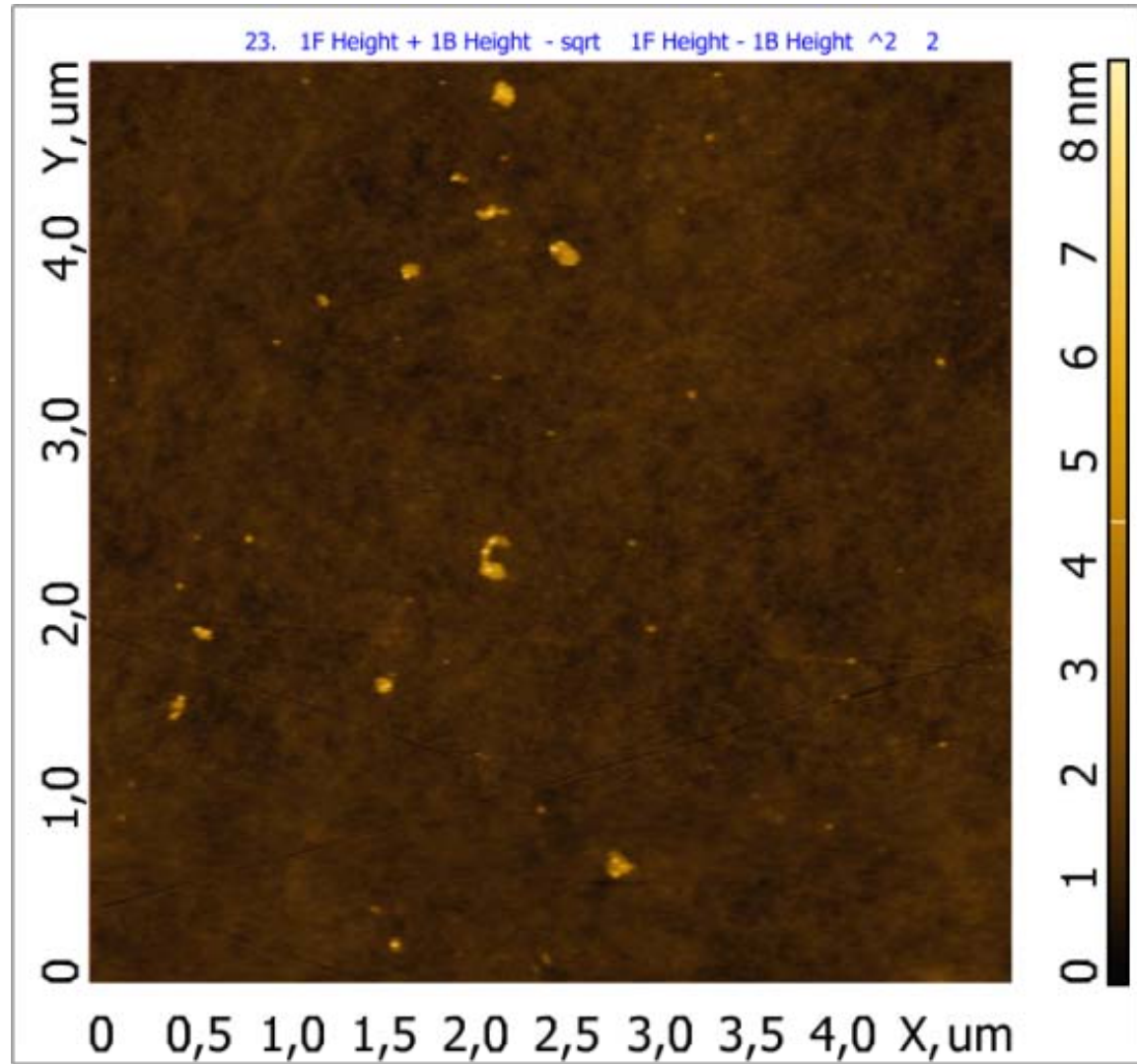
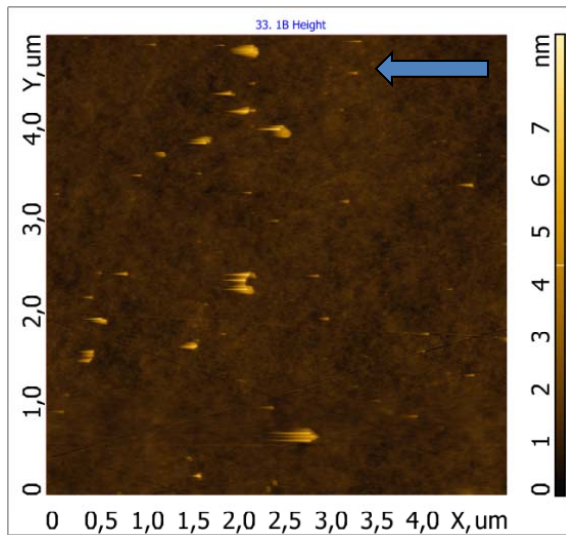
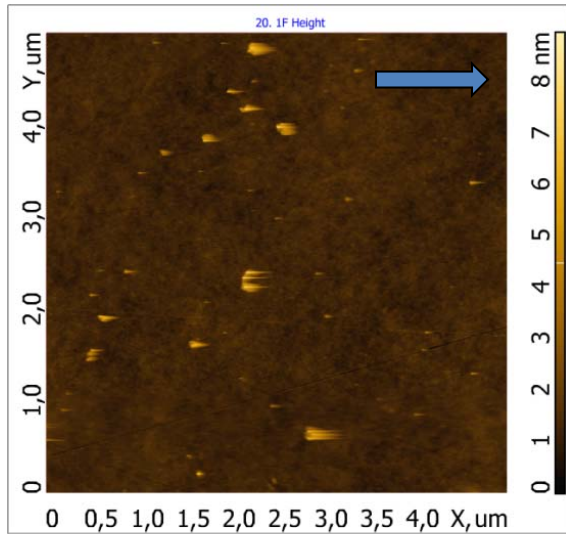
$$U = k_i(Mag_0 - SP) \cdot t + U_0 \quad t_3 < t < t_4$$



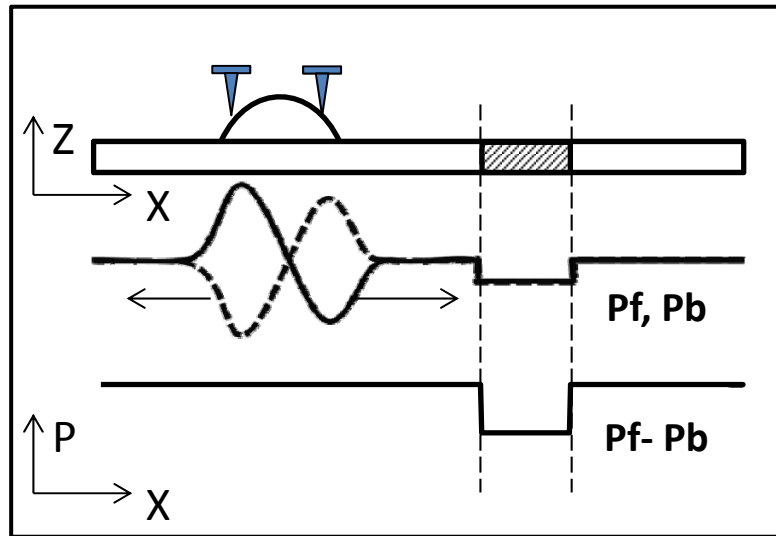
Parachuting effect in tapping mode AFM



Parachuting effect in tapping mode AFM

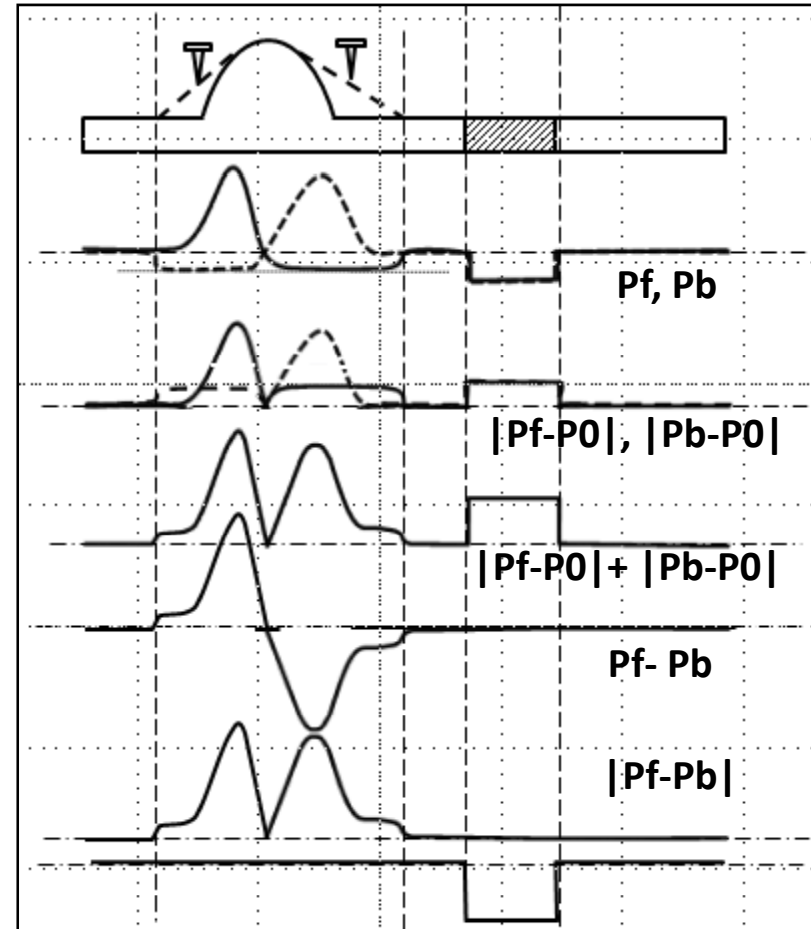


Parachuting and topography effects in phase contrast



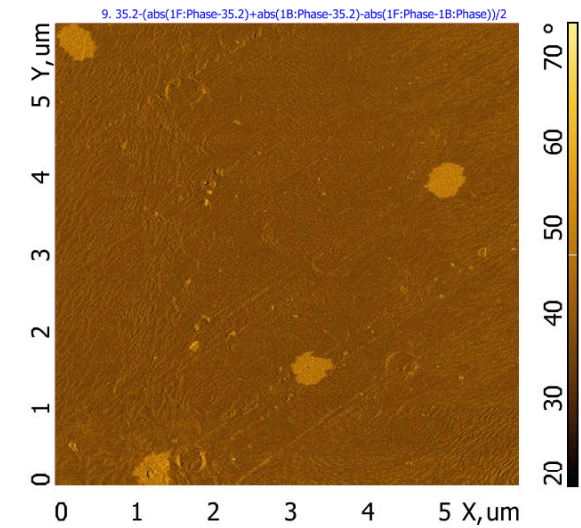
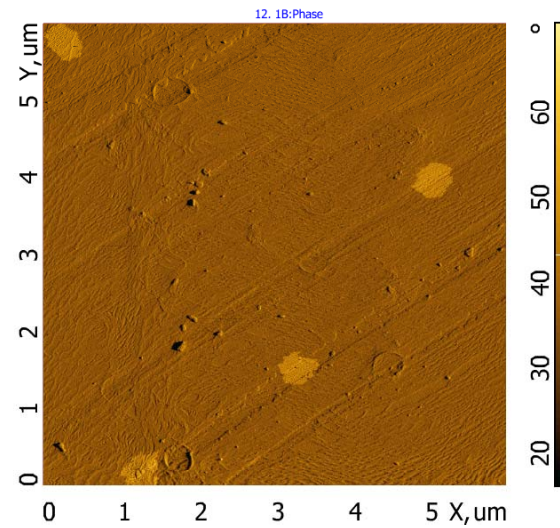
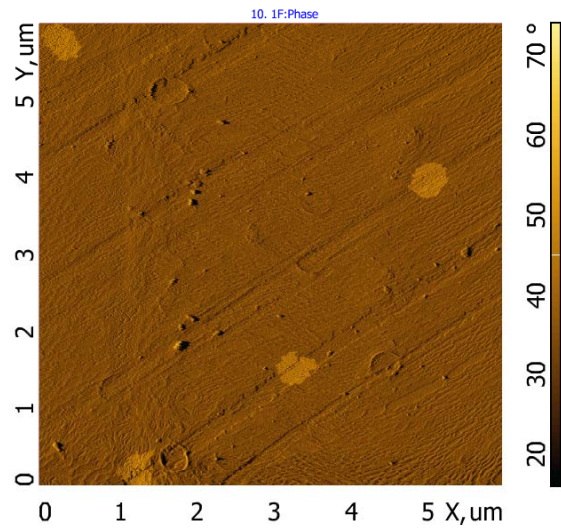
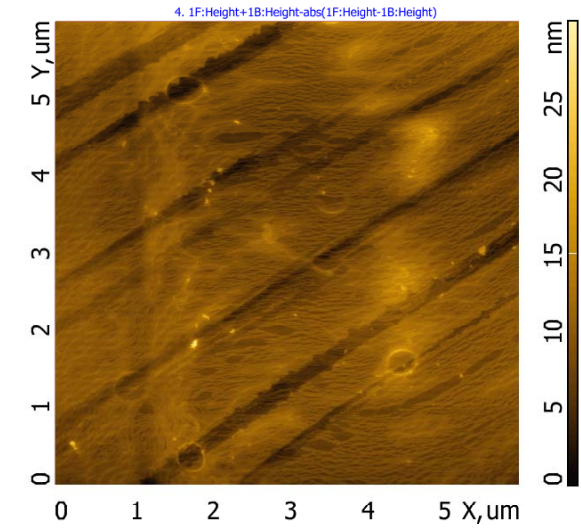
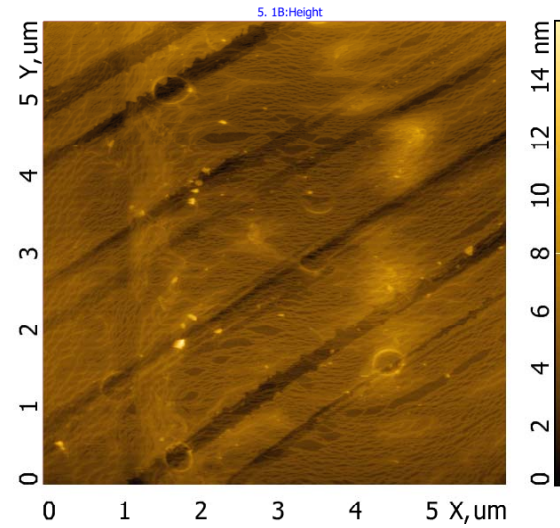
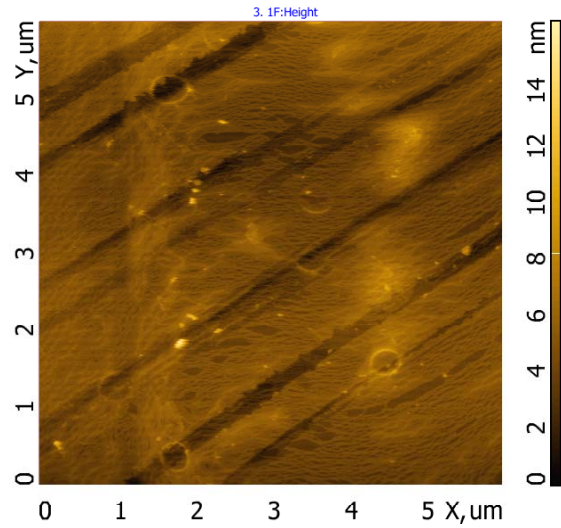
Phase signal (no parachuting) and compensation of topography influence

$$P_o + 0.5 * [|P_f - P_b| - (|P_b - P_o| + |P_f - P_o|)]$$

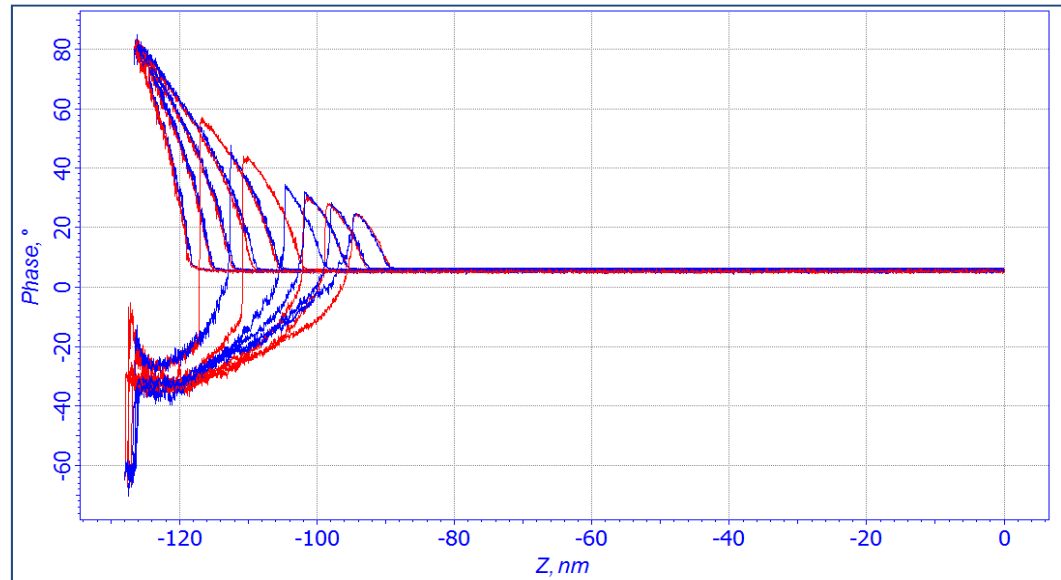
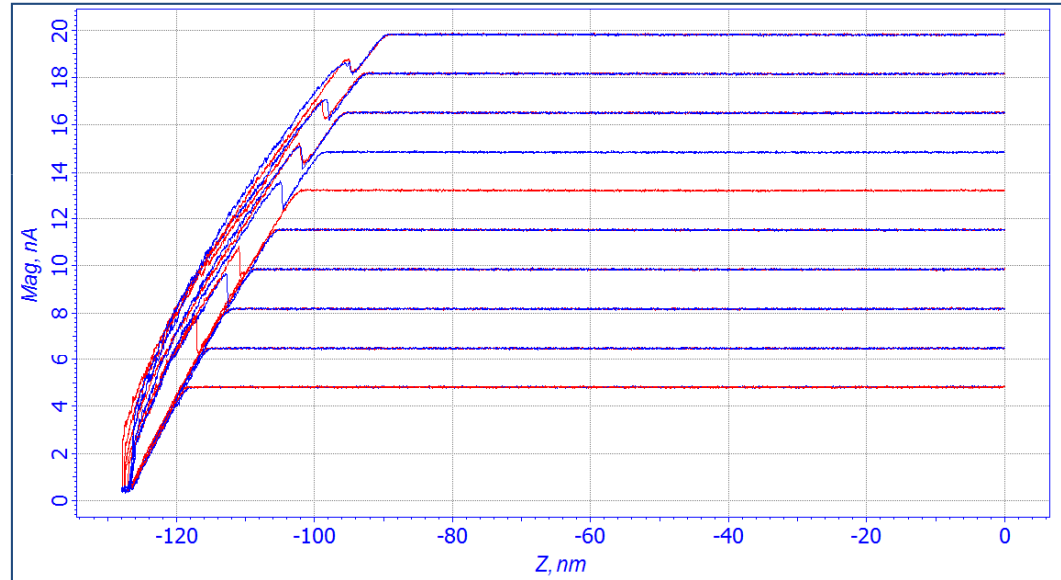


Phase signal in case of parachuting and its compensation

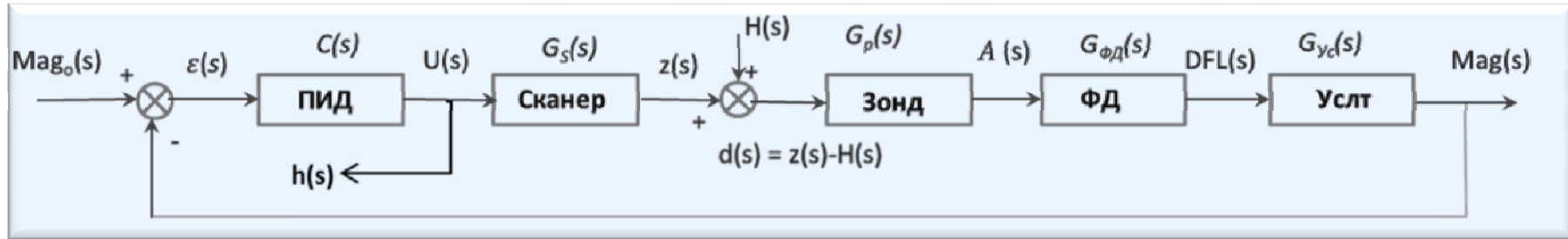
Parachuting and topography effects in phase contrast



Mode switching in tapping mode AFM



Feedback gain optimization in tapping mode AFM



$$\varepsilon = SP - Mag$$

$$\frac{dU}{dt} = k_i \cdot \varepsilon(t)$$

$$H = k_s U$$

$$Mag = k_p (H - h)$$

$$\tau_0 = \frac{1}{k_i k_p k_s}$$



$$V_x \tau_0 \cdot \frac{dH(x)}{dx} + H(x) = h(x)$$

$$\varepsilon [\text{nm}] = V_x \tau_0 \cdot \frac{dH(x)}{dx}$$

Feedback gain optimization in tapping mode AFM

- Minimize **Error** signal
- Avoid mode hopping
- Avoid **Mag** signal saturation

- Integral feedback gain optimization: minimization of RMS of MAG:

$$\varepsilon = \frac{\alpha}{k_i} + \beta k_i + \gamma k_i^2 + \delta$$

- Avoid mode switching: setting amplitude so that there is no mode switching, that can be controlled using **Phase** signal
- Avoid **Mag** signal saturation: if saturation happens – decrease Set Point; if Set Point is less than 50% of free amplitude – adjust speed of scanning

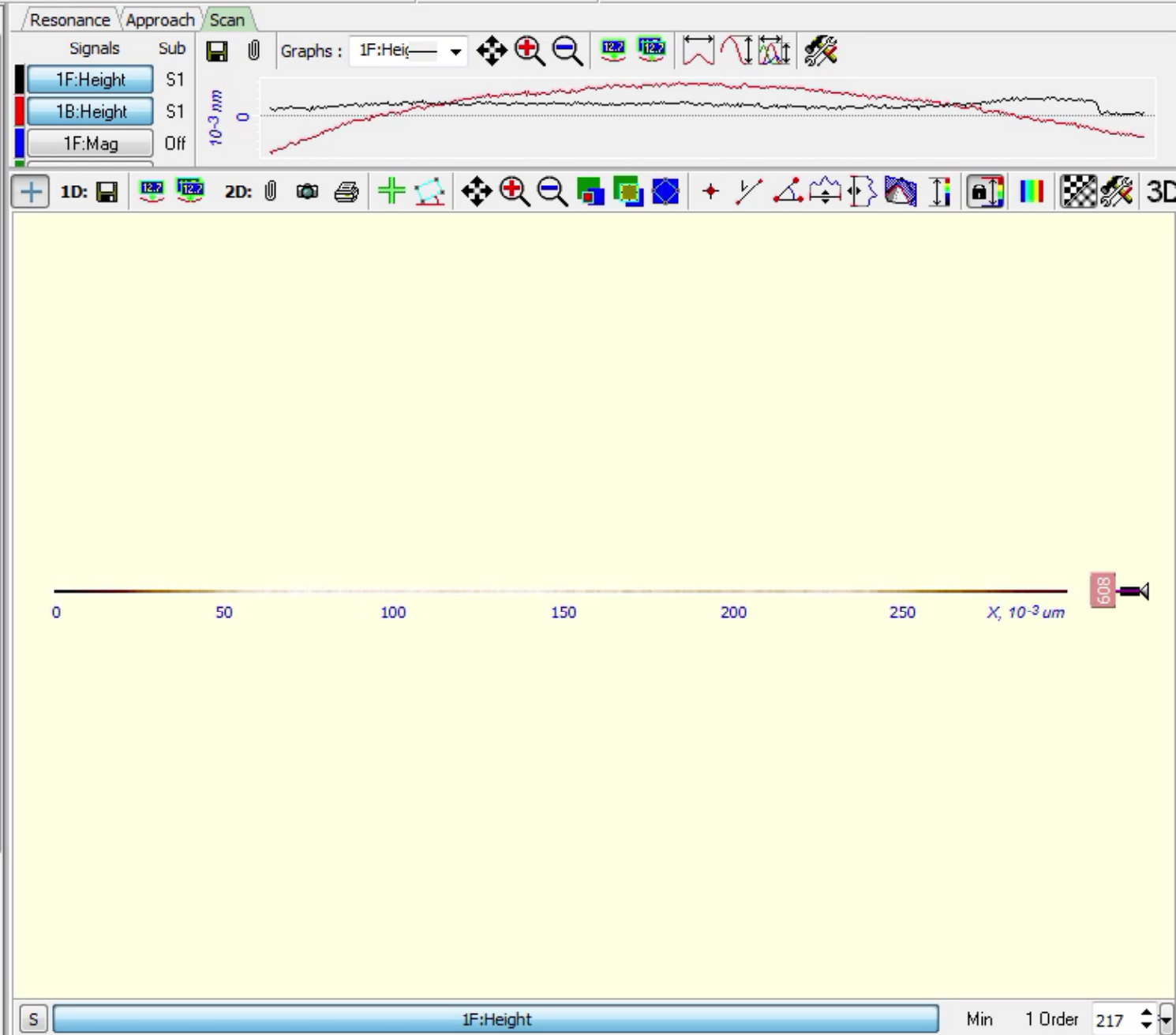
$$\varepsilon[\text{nm}] = V_x \tau_0 \cdot \frac{dH(x)}{dx}$$

Run Restart Mode: SemiContact Topo Opt Direction: ▼ Quick Sections
 Rate: 1.40000 Hz Time: 0:06:06 Area Params +

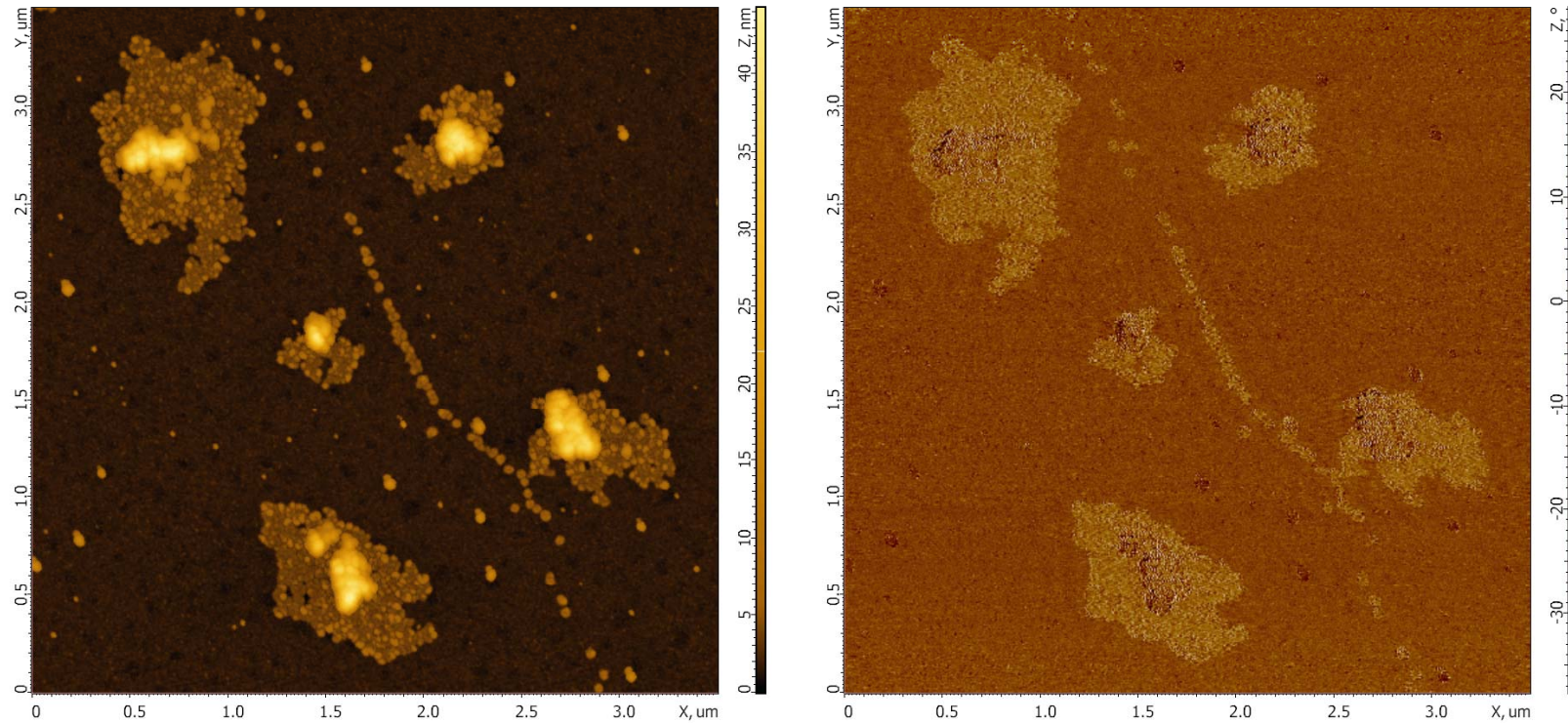
ScanTronic
Start
 Status: StandBy
 F = 0.058 nN Save data
 Regime: Attraction Amp limit: 30
Main options
 Optimization mode: Base Start Mode: Current
 N prescan: 1 Amp ON
Optimized parameters

	Initial	Actual
Amp	0.0010	0.0442
LockGain	20.0	38.4
zI	0.55	0.20
zP	7.00	9.80
zSP	0.900	9.800
Rate	1.4000	1.4000
lpfMag	11000.0	1000.0
Shift	0	-8

Save set
Quality control
 r(Height) = 1.0000
 RMS(Mag) = 0.0092
 RMS(Mag) = 0.0092

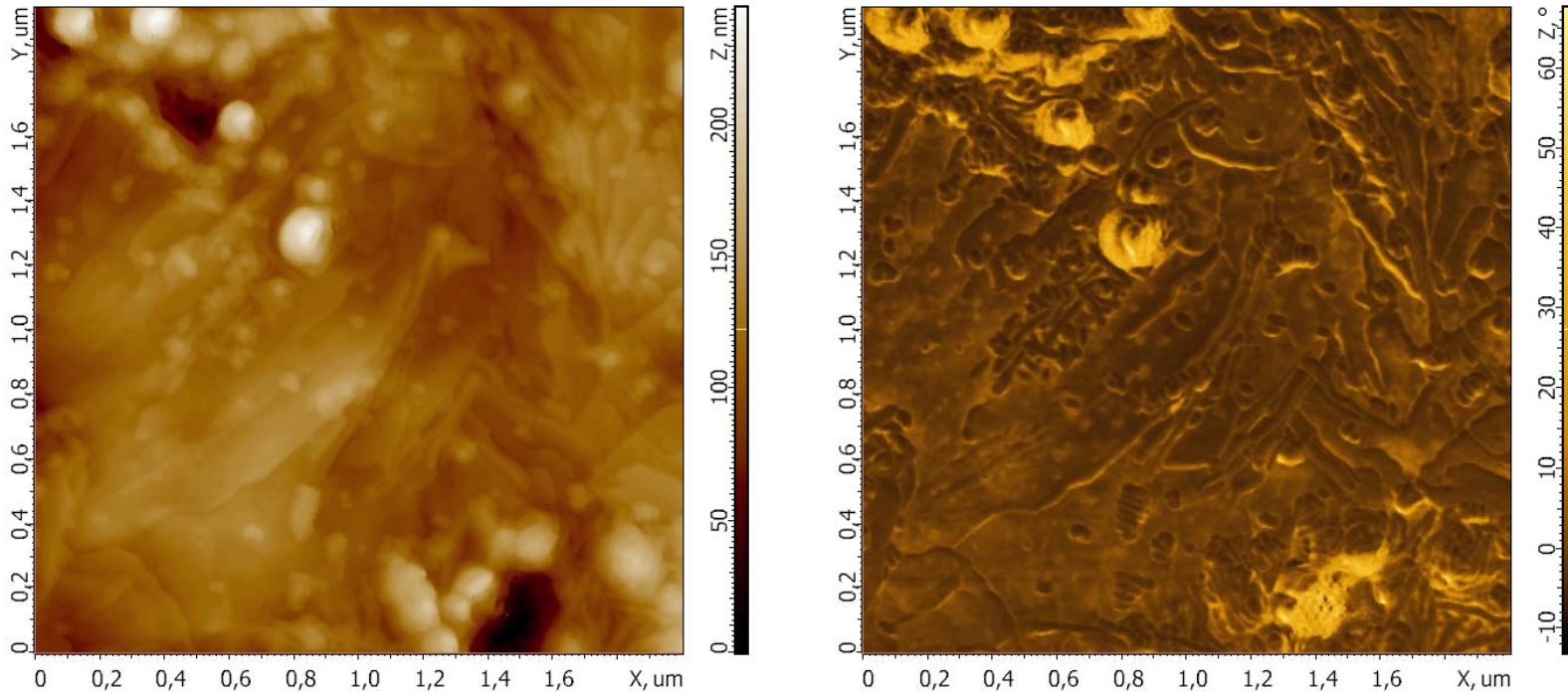


Scan Tronic: Examples of application



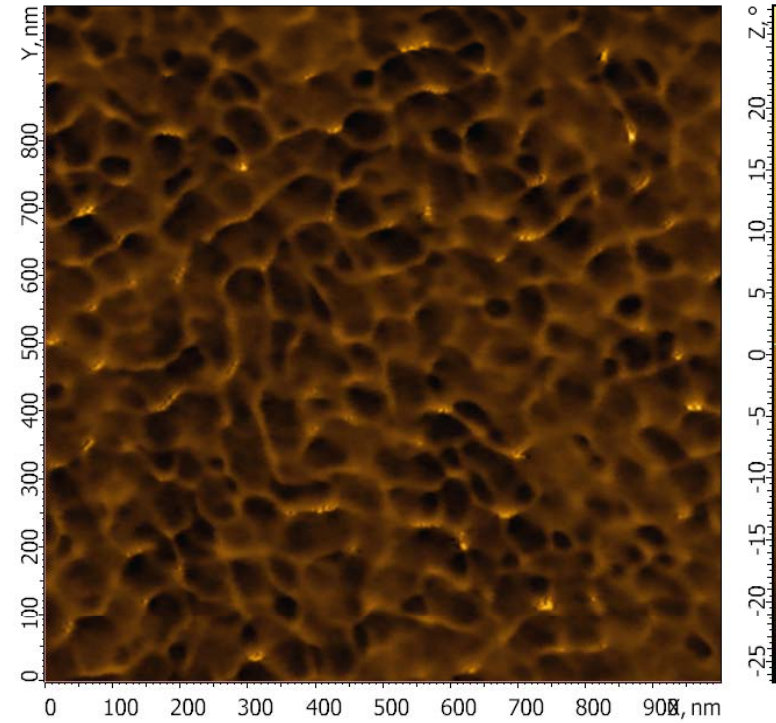
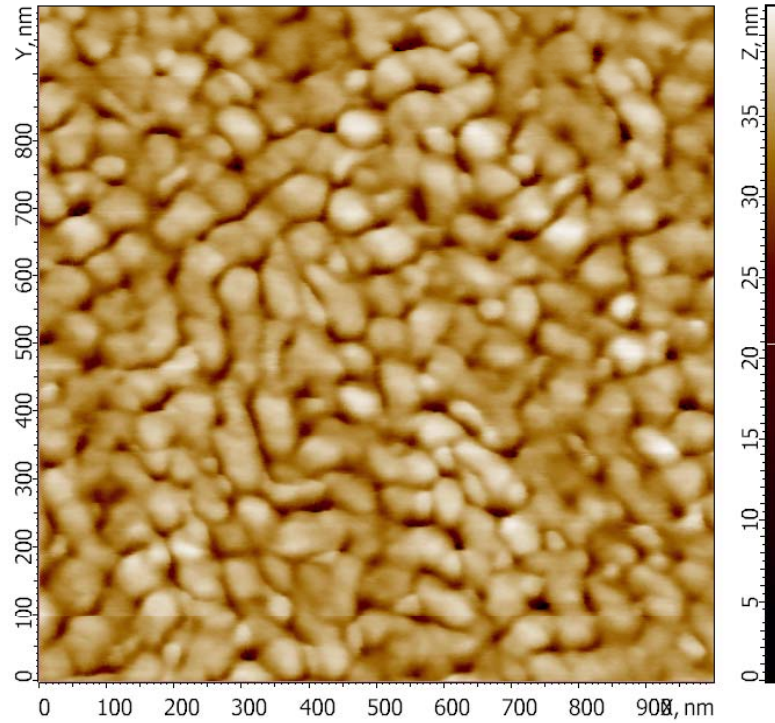
Fluoroalkanes $F_{14}H_{20}$ on Si. Left – topography, right – phase contrast
Scan size $3.5 \times 3.5 \mu\text{m}$

Scan Tronic: Examples of application



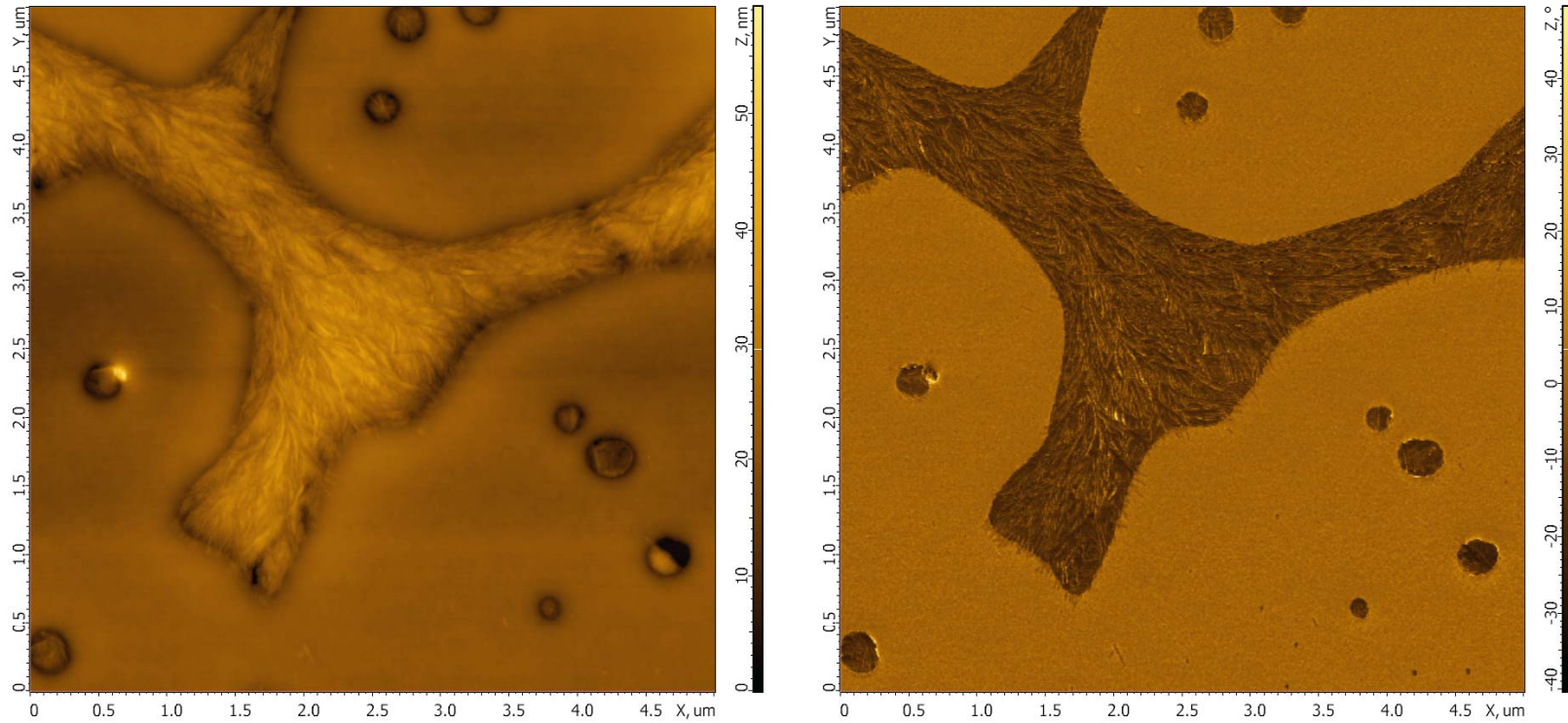
HDPE. Left – topography, right – phase contrast
Scan size $2 \times 2 \mu\text{m}$

Scan Tronic: Examples of application



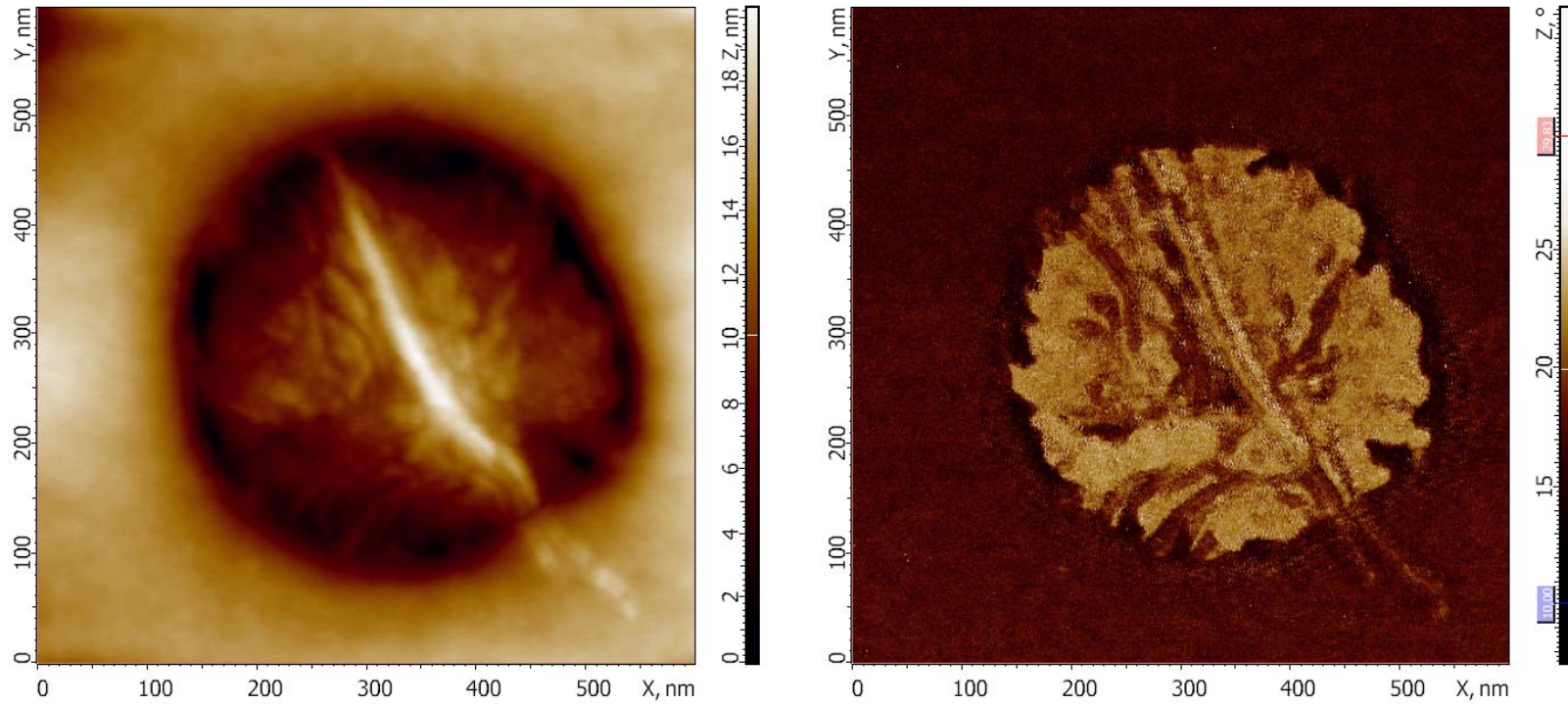
PS-b-PMMA. Left – topography, right – phase contrast
Scan size $1 \times 1 \mu\text{m}$

Scan Tronic: Examples of application



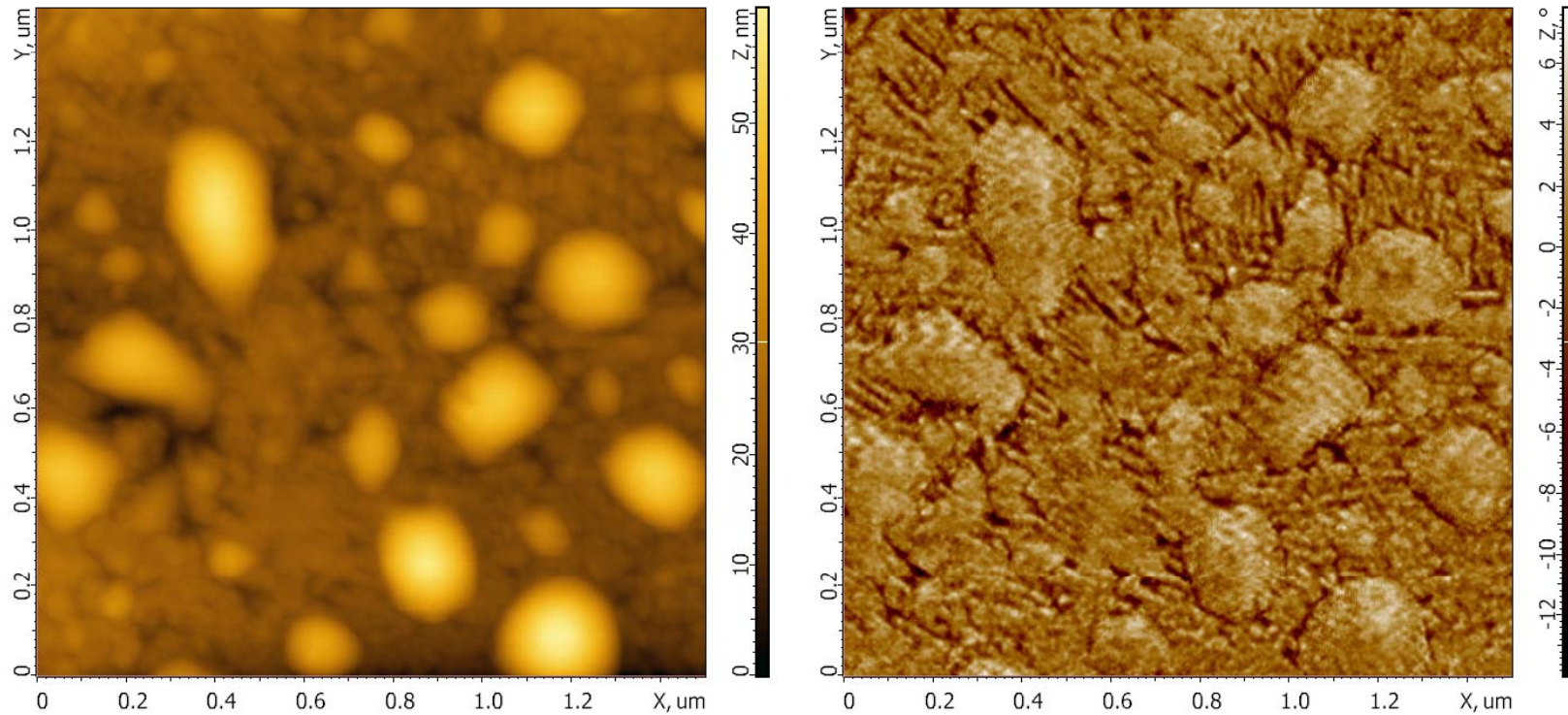
PVDF-sPS. Left – topography, right – phase contrast
Scan size $5 \times 5 \mu\text{m}$

Scan Tronic: Examples of application



PVDF-sPS. Left – topography, right – phase contrast
Scan size 600×600 nm

Scan Tronic: Examples of application



TPV. Left – topography, right – phase contrast
Scan size $1.5 \times 1.5 \mu\text{m}$

Setting initial parameters



Setting initial parameters: machine learning

Topography, p-p, nm	Roughness	Stiffness	Stickiness	Charge
<20	Unknown	Unknown	Unknown	Unknown
20-50	Low	Low	Low	Low
50-100	Mid	Mid	Mid	Mid
100-250	High	High	High	High
250-500				
>500				

Buttons: Set as Actual, Set as Initials

Before experiment

Scan procedure is over. Please, select the sample features and save adjuster's parameters

Sample features:

Roughness: Mid

Stiffness: Low

Stickiness: High

Static charge: Semiconductor

Comments:

tgz1

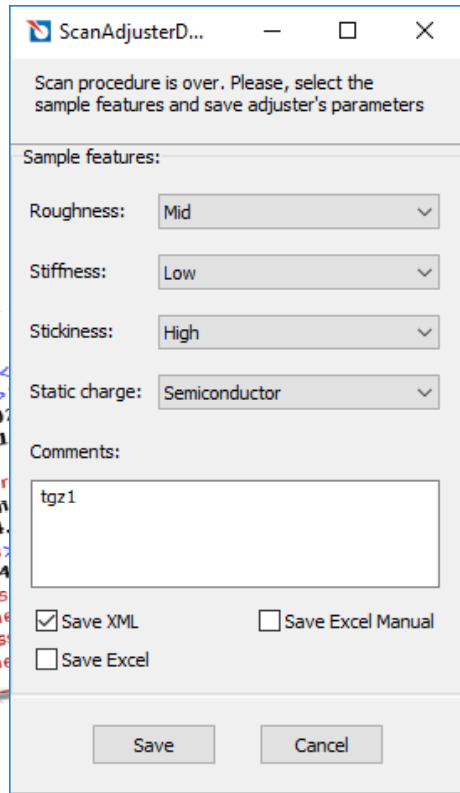
Save XML Save Excel Manual
 Save Excel

Buttons: Save, Cancel

After experiment

Setting initial parameters: machine learning

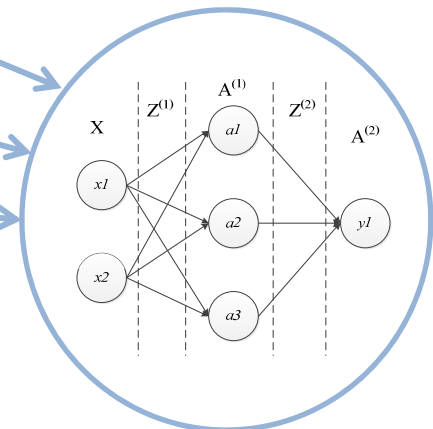
Saving



Learning

Based on the backpropagation method using the BFGS algorithm (Broyden-Fletcher-Goldfarb-Shanno)

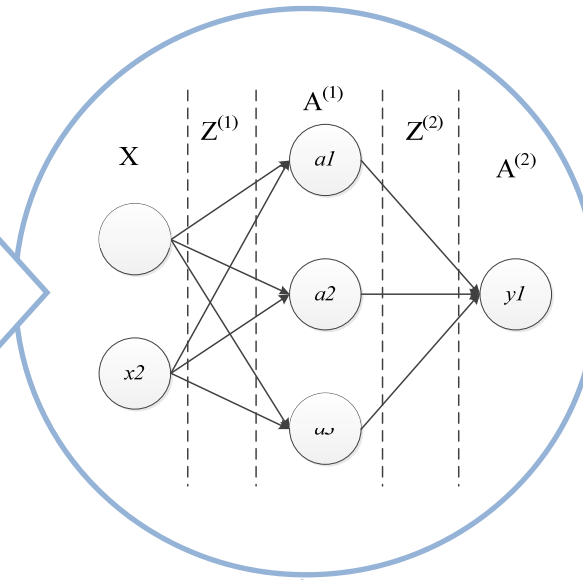
The search for the minimum of the objective function makes it possible to find and adjust the optimal synapse weights



Setting initial parameters: machine learning

f – cantilever resonant frequency
 K – cantilever stiffness
 Q – Q-factor of the cantilever
 Nx – number of pixels
Scan size

Input



Output

P_0 and I_0 feedback gains
 SP_0 – Set Point
 V_0 – Scan rate

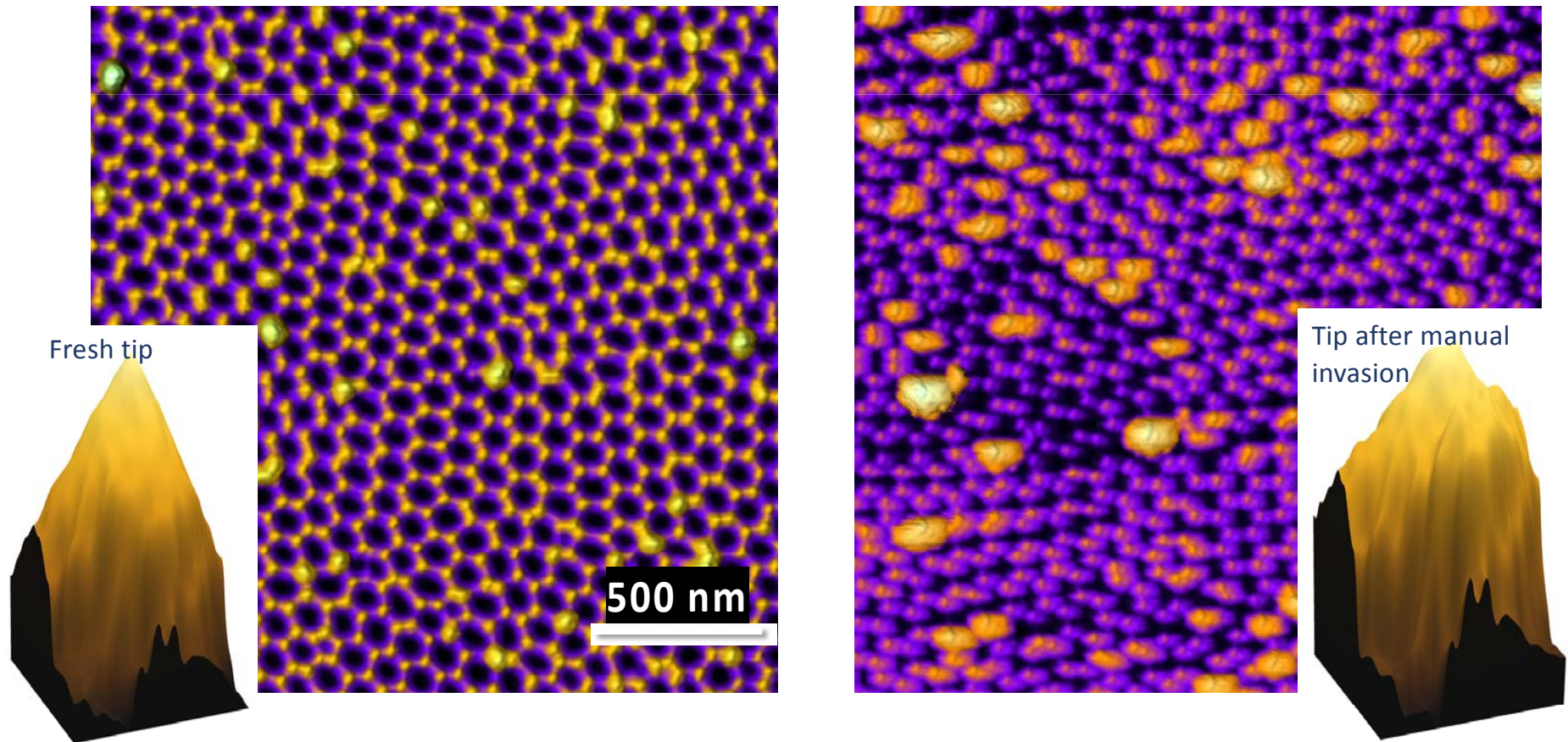
Sample parameters (stickiness, charge, roughness and stiffness)





ScanTronic

Scan Tronic: Examples of application



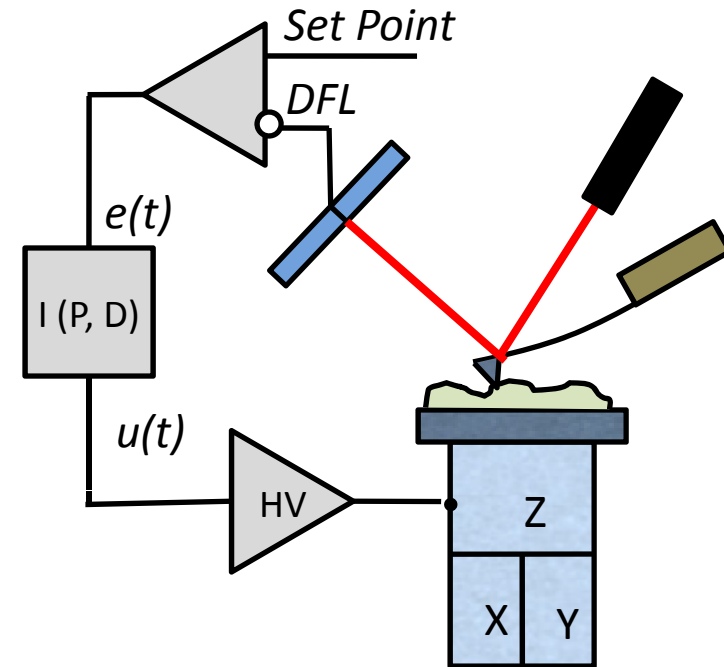
Al_2O_3 - "Grater" sample for tips.
Left – topography, ScanTronic used, right – manual attempt to adjust scanning parameters



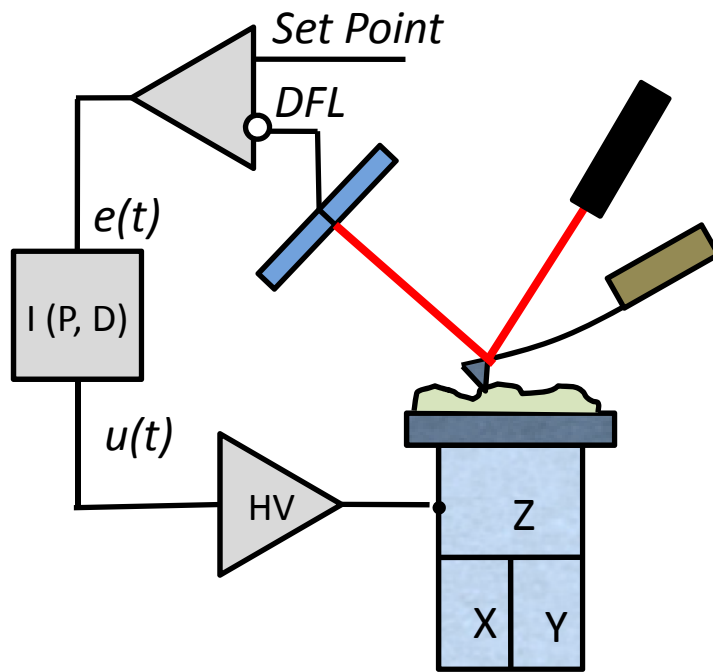
Rapid Scan

Fast scanning and High-speed scanning

- **"High-speed AFM"** is usually referred to video-rate AFM, working with the scan speed of 10 – 100 frames per second:
 - Small sample size
 - Topography imaging only
 - Very complex to operate with
 - Small FOV
- **"Fast scan AFM"** is usually referred to
 - Smaller FOW (compare to regular AFM)
 - Scan rates ~ 10 lines per second

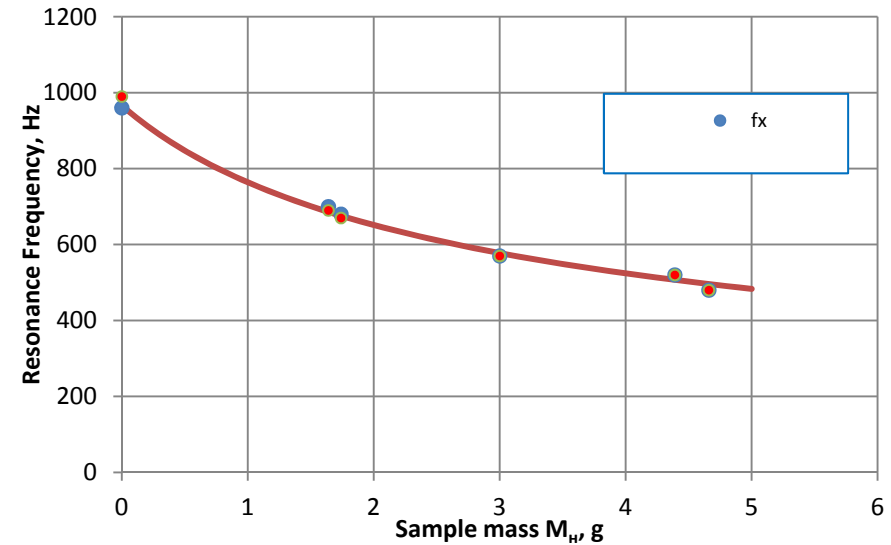


Fast scanning

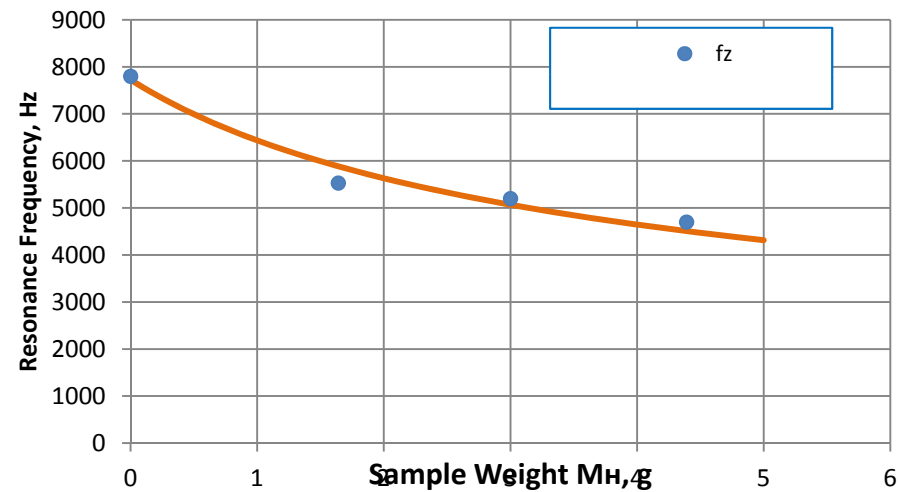


$$f_R = \frac{1}{2\pi} \sqrt{\frac{k}{(M_0 + M_H)}}$$

k – effective spring constant of the scanner,
 M_0 - effective mass of the scanner,
 M_H - mass of load



Scanner resonant frequency (XY)

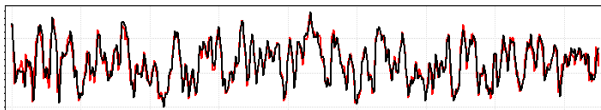
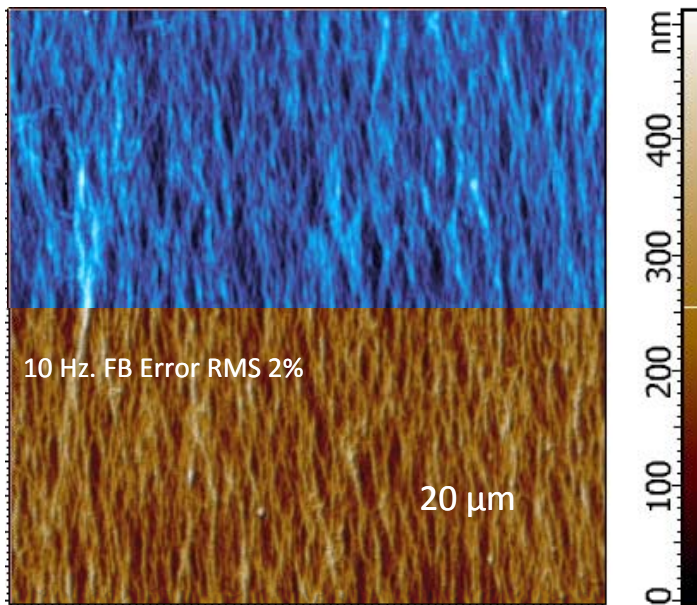


Scanner resonant frequency (Z)

Rapid Scan 100

Rapid Scan 100 technology is a combination of mechanical design and high-end digital electronic solutions which allows to speed up your AFM by an order of magnitude keeping 90 μm in-plane scanning range.

All three axes are equipped with high-precision closed-loop capacitive sensors.



90 \times 90 \times 0,5 μm image of collagen fibers captured @ 1 & 10Hz scanning rates



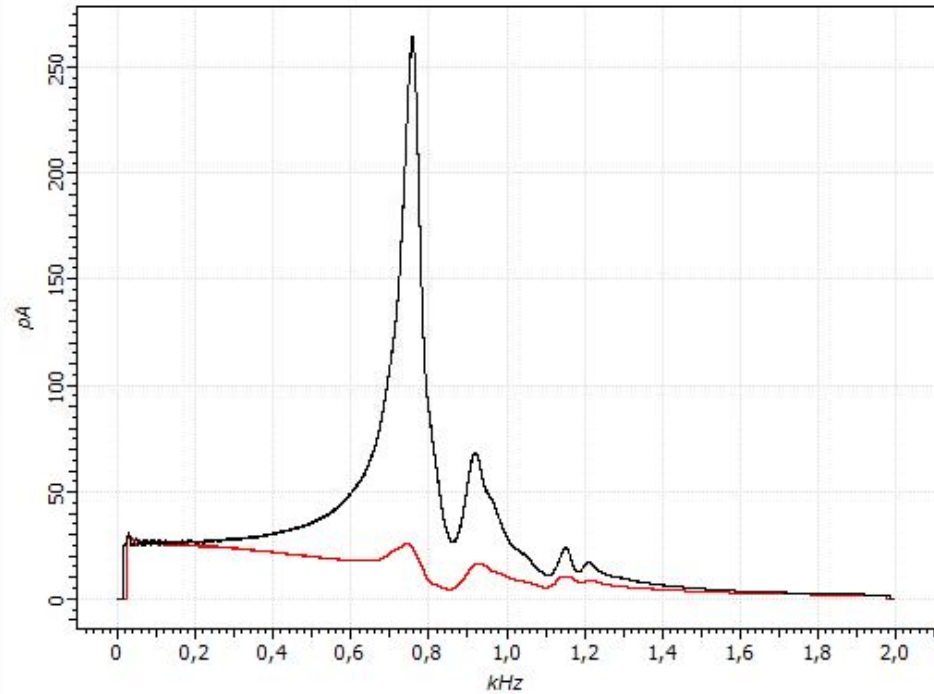
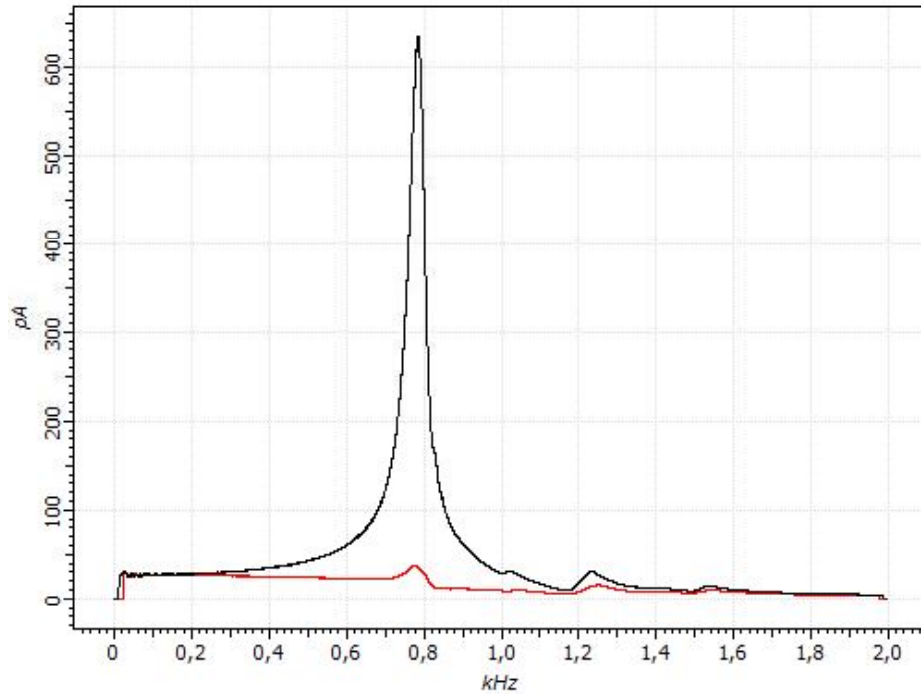
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Parameter	Value
Travel range (XY/Z), μm	90×90×4 \pm 10%
Closed loop sensors (XYZ)	Capacitive
Sample size, \varnothing mm	15
Vertical noise floor, μm	30
XY position noise (Closed Loop), nm	0,1
Nonlinearity, %	0,1
Resonance Frequency (XY/Z), kHz	0,8/12
Active resonance damping	+

Rapid Scan 100: damping of scanner resonance



Damping of X (left) and Y (right) scanner resonances by digital filtration

Summary

- **ScanTronic™** technology allows to eliminate common AFM artefacts and drastically improve quality of AFM results
- **ScanTronic™** is lowering significantly cantilever consumption for any AFM lab
- Together with **ScanTronic™**, **RapidScan™** technology increase scan rates up to ~ 10 times without compromise with maximum XY visible area

Acknowledgements

- **Dr. Yury Bobrov**
- **Pavel Vinar**
- **Andrey Gruzdev**
- **Dr. Stanislav Leesment**



Spring Life Shows



MARCH MEETING 2019
MARCH 4-8 BOSTON, MA



Booth #732



2019 **MRS**[®]
SPRING MEETING & EXHIBIT
April 22–26, 2019 | Phoenix, Arizona

Booth #226



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March 31 - April 4, 2019 | Orlando, FL

ACS National Meeting & Expo



Thank you!